

Chapter 6 Errata corrigenda

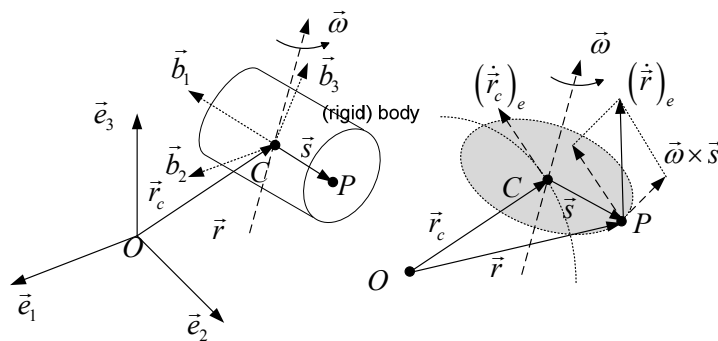
Erratum, page 239-240, Eqs. (6.8) and (6.9) (August 19, 2019)

Corrigendum

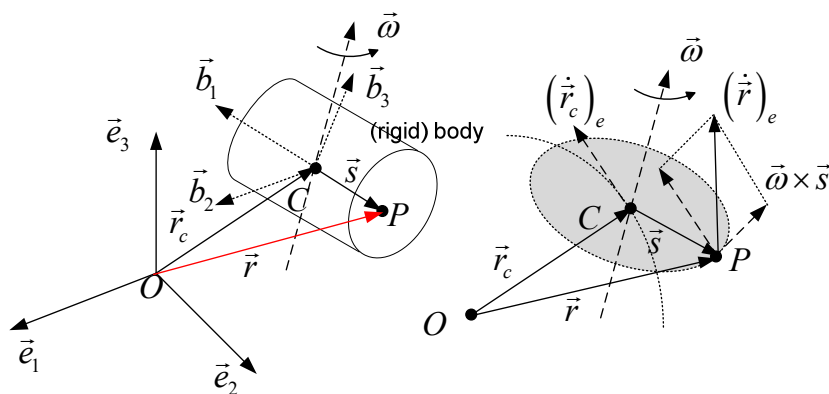
$$\dot{\boldsymbol{\theta}}(t) = \frac{\boldsymbol{\theta}}{\mathcal{G}} \dot{\mathcal{G}} + \frac{\mathcal{G}}{2} \left( \cot(\mathcal{G}/2) \boldsymbol{\omega}_b + \frac{\boldsymbol{\theta}}{\mathcal{G}} \times \boldsymbol{\omega}_b \right) - \frac{\boldsymbol{\theta}}{2} \cot(\mathcal{G}/2) \dot{\mathcal{G}}, \quad (6.8)$$

$$\dot{\boldsymbol{\theta}}(t) = \left( I + \frac{1}{2} \boldsymbol{\theta} \times + \frac{1}{\mathcal{G}^2} \left( 1 - \frac{\mathcal{G}}{2} \cot(\mathcal{G}/2) \right) (\boldsymbol{\theta} \times)^2 \right) \boldsymbol{\omega}_b(t) \quad (6.2)$$

Erratum, page 243, Figure 6.1 (August 19, 2019)

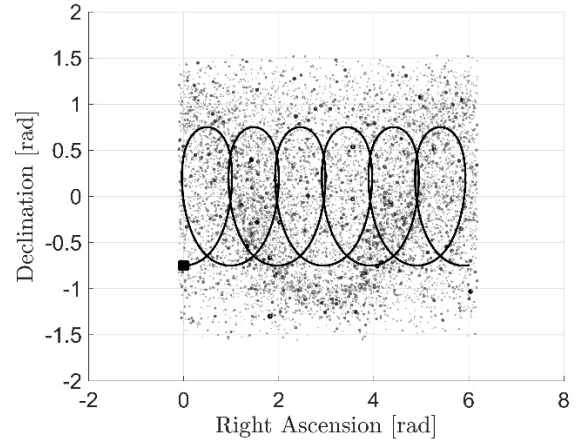


Corrigendum



Erratum Figure 6.5, right

Corrigendum



Erratum, Section 6.4.1, page 258

Let us apply to the frame of reference represented by  $\mathfrak{q}(t)$ , a small rotation  $\{\Delta\phi(t), \vec{e}(t)\}$ , where  $\Delta\phi$  is the integrated angular rate  $\omega(t)\Delta t$  during  $\Delta t$ :

$$\Delta\phi(t) = \int_t^{t+\Delta t} \nu(\tau) d\tau = \omega(t) \Delta t. \quad (6.69)$$

Corrigendum

Let us apply to the frame of reference represented by  $\mathfrak{q}(t)$ , a small rotation  $\{\Delta\mathfrak{g}(t), \vec{e}(t)\}$ , where  $\Delta\mathfrak{g}$  is the integrated angular rate  $\omega(t)\Delta t$  during  $\Delta t$ :

$$\Delta\mathfrak{g}(t) = \int_t^{t+\Delta t} \nu(\tau) d\tau = \omega(t) \Delta t. \quad (6.69)$$

Erratum, page 265 (August 19, 2019)

$$\begin{aligned} \tilde{\mathfrak{q}}_r &= (\mathfrak{q}_r^{-1} \otimes \hat{\mathfrak{q}}) \otimes (\hat{\mathfrak{q}}^{-1} \otimes \mathfrak{q}) = \mathfrak{e}_r \otimes \tilde{\mathfrak{q}} \cong \tilde{\mathfrak{q}} \\ \mathfrak{e} &= (\mathfrak{q}_r^{-1} \otimes \hat{\mathfrak{q}}) \otimes (\hat{\mathfrak{q}}^{-1} \otimes \tilde{\mathfrak{q}}) = \mathfrak{e}_r \otimes \tilde{\mathfrak{q}}_m \cong \tilde{\mathfrak{q}}_m \end{aligned} \quad (6.97)$$

Corrigendum

$$\begin{aligned} \tilde{\mathfrak{q}}_r &= (\mathfrak{q}_r^{-1} \otimes \hat{\mathfrak{q}}) \otimes (\hat{\mathfrak{q}}^{-1} \otimes \mathfrak{q}) = \mathfrak{e}_r \otimes \tilde{\mathfrak{q}} \cong \tilde{\mathfrak{q}} \\ \mathfrak{e} &= (\mathfrak{q}_r^{-1} \otimes \hat{\mathfrak{q}}) \otimes (\hat{\mathfrak{q}}^{-1} \otimes \tilde{\mathfrak{q}}) = \mathfrak{e}_r \otimes \mathfrak{e}_m \cong \mathfrak{e}_m \end{aligned} \quad (6.97)$$